

Development of a method of rain gauge network optimization based on Intensity-Duration-Frequency results

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Abstract

In this work, a method using intensity-duration-frequency curves (IDF) is developed in a context of robust optimisation in order to identify the best locations to implement new rain gauges with respect to rainfall variability characteristics. The advantage of robust optimisation is to derive design solutions that yield networks which work 'adequately', when considering various rainfall events. Thus, the robust optimisation approach overtakes the problem of selecting representative rainfall events to build the optimisation process. The presentation develops an original methodology based on Montana IDF model parameters. The latter are assumed as geostatistical variables and their spatial interdependence is taken into account through the adoption of cross-variograms in the kriging process. To assess the optimal location of new monitoring stations with, as point of departure an existing rain gauge network, the objective function is based on the mean spatial kriging variance and the variogram model using the so-called variance-reduction method. Various return periods as well as two time horizons (short term and long-term) are considered to build a robust objective function which is further minimized using simulated annealing algorithm. Application concerns the case study of north Tunisia augmentation rain gauge network. Results of IDF curves estimated using a network of 14 stations are analyzed. Robust optimization optimal networks are compared to those obtained assuming the following mono objective criteria: minimization of the mean spatial kriging variance of rainfall intensity and erosivity factor patterns using data from a single extreme rainfall event occurred in March 1973.

Objectives

- > develop a methodology of rainfall network optimization based on the well-known Montana IDF model.
- > derive design solutions that yield networks which work 'adequately', when considering various rainfall events
- > compare results to those of classical mono objective criteria based on the analysis of 1h-rainfall intensity observations and erosivity factor observations during a given extreme rainfall event.

Methodology

* A number of candidate stations is first assumed. The analysis is run for a given size of the optimal network. The problem is to find the best locations. On the other hand, the point of departure of the study is an existing network of 13 stations which will be extended.

❖ **The IDF curves Montana model are adopted to conduct the analysis:** $l(t, T) = a(T) \cdot t^{b(T)}$
 - the dependence structure between the parameters $a(T)$ and $b(T)$ is described using their cross variogram $\gamma_{a(T)b(T)}(h)$:

$$\gamma_{a(T)b(T)}(h) = \frac{1}{2 \cdot N(h)} \sum_{i=1}^{N(h)} [a(x_i+h) - a(x_i)] [b(x_i+h) - b(x_i)]$$

and dispersion coefficient graph $r_{a(T)b(T)}(h) = \frac{\gamma_{a(T)b(T)}(h)}{\sqrt{\gamma_{a(T)a(T)}(h) \cdot \gamma_{b(T)b(T)}(h)}}$

- The variable of interest is set to be $a(T)$ (using $b(T)$ as a function of $a(T)$) (return periods $(T = 2, 5, 10, 20, 50, 100$ years) thus covering a broad panoply of risk situations.

❖ **Kriging is adopted as method to design the optimal network:**

- Kriging with external drift is used to derive the parameter $a(T)$ throughout the study area; parameter $b(T)$ obtained by ordinary kriging is assumed as external drift

❖ **Two time horizons:** in short term ($N = 5$ years) and in long-term ($N = 30$ years)) are considered to build a robust objective function which is further minimized using simulated annealing algorithm

❖ **The objective function (OF)** is based on the mean spatial kriging variance with a grid mesh of 4 km size (covering an area of 21000 km²) using the so-called variance-reduction method:

$$OF = Prob_{(2years)} \cdot (OF_{ref(2years)} - OF_{(2years)})^2 + Prob_{(5years)} \cdot (OF_{ref(5years)} - OF_{(5years)})^2 + Prob_{(50years)} \cdot (OF_{ref(50years)} - OF_{(50years)})^2$$

Where $Prob_{(Tyears)}$ is exceedance probability of the event of return period T (in years) with $Prob_{(2years)} + Prob_{(5years)} + Prob_{(50years)} = 1$

- Standardization of the mean spatial kriging variance is obtained by using the interquartile difference of the field of the variances of error of $a(T)$:

$$FO(T ans) = \frac{\sum_{i=1}^n (\sigma_{a(Tans)}^2)^2}{n} \left/ \left(\sigma_{75\%a(Tans)}^2 - \sigma_{25\%a(Tans)}^2 \right) \right.$$

$\sigma_{75\%a(Tans)}^2$ is the 75% percentile of the pattern of the variance of kriging errors of $a(T ans)$

$\sigma_{25\%a(Tans)}^2$ is the 25% percentile of the pattern of the variance of kriging errors of $a(T ans)$

$OF_{ref(T ans)}$ is the value of the objective function obtained for every return period independently of the other return periods. It is taken as reference.

❖ **Various Scenarios** are simulated where the size of the initial network is increased by 25

(Scenario1), 50 (Scenario 2) and 100 % (Scenario 3), considering 40 candidate stations. Another

application is shown for increasing the network to meet WMO requirement, considering 60 candidate

stations (Scenario 4). The two time horizons are simulated for each scenario.

Case study and Data

- Data cover the North of Tunisia area (Mediterranean coast belonging to Medjerda basin)
- **Figure 1** reports the study area together with the pluviograph networks involved in 1973 extreme event and candidate stations.
- Intensity-duration-frequency curves (IDF) are reported for 14 stations of the study area according to the study of ST2i (2007).
- Montana IDF model parameters estimated by ST2i (2007) are presented in **Table 1**

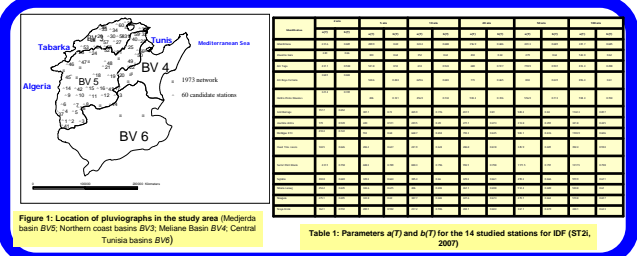


Figure 1: Location of pluviographs in the study area (Medjerda Basin BV3, Northern coast basin BV3, Medjerda Basin BV4, Central Tunisia basins BV6)

Station	a(T)	b(T)
1	0.004	30
2	0.008	40
3	0.010	40
4	0.014	40
5	0.016	40
6	0.018	40
7	0.004	30
8	0.008	40
9	0.010	40
10	0.014	40
11	0.016	40
12	0.018	40
13	0.004	30
14	0.008	40

Table 1: Parameters a(T) and b(T) for the 14 studied stations for IDF (ST2, 2007)

Results

(a) Interdependence of the parameters $a(T)$ and $b(T)$ as reflected by erratic fluctuation of $r_{a(T)b(T)}(h)$ (**Figure 2**); $r_{a(T)b(T)}(h)$ are assumed constant for all T values.

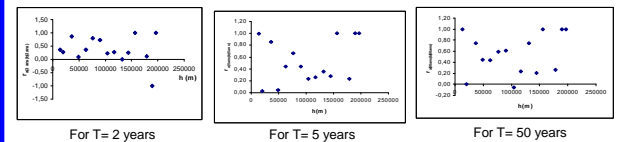


Figure 2: Fluctuation of $r_{a(T)b(T)}(h)$ supports interdependence assumption

(b) Structural analysis of the parameters $a(T)$ and $b(T)$ results in three groups where the variograms are similar: **group 1 (T= 2 years)**; **group 2 (T= 5, 10, 20 years)**; **group 3 (T= 50, 100 years)**; Representatives of each group are: T=2 years, T=5 years and T=50 years; Ranges of $a(T)$ and $b(T)$ variability extent from 30 km to 50 km (**Table 2**)

Return period (years)	Sill a (Sill b)	Range a km (Range b km)
2	0.004 (15000)	30 (40)
5	0.008 (32000)	40 (50)
10	0.010 (45000)	40 (45)
20	0.014 (50000)	40 (50)
50	0.016 (110000)	40 (50)
100	0.018 (110000)	40 (50)

Table 2: Adjusted sills and ranges for a(T) and b(T) assuming spherical variogram models

(c) The comparison of the resulting robust networks obtained successively for the two time horizons (short term and long-term) shows that they are similar for scenario 1. For scenario 2, the two robust networks differ only by one station over the two time horizons (short term and long term). For scenario 3, the two robust networks obtained successively for the short term and long term horizons differ only by 2 stations out of 13. For scenario 4, they differ by 7 stations out of 21 (**Figure 3**).

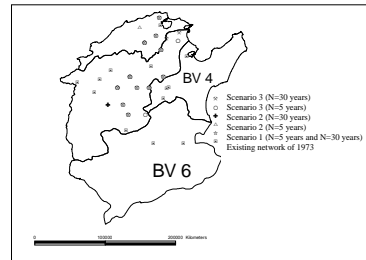


Figure 3: Configuration of optimal networks

(d) The comparison of the robust networks to the mono objective optimal networks obtained successively for the rainfall intensity and the erosivity factor mapping for March 1973 shows that the resulting networks are very different for the two horizons and for all scenarios. Results reflect the decreasing of the objective function when the size of the final network (**Figures 4 and 5**) is increased and that the gain in augmenting the network size is less perceivable using the robust estimation than using the mono objective criteria. The latter give rise to optimal objective function values that are lower or equal to that obtained in the case of the robust optimisation (**Figures 4 and 5**).

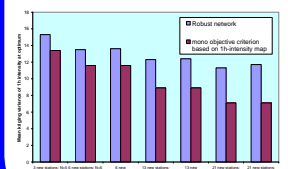


Figure 4: Mean spatial kriging variances obtained by the robust network and by the mono objective criterion for Rainfall intensity mapping

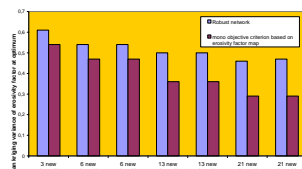


Figure 5: Mean spatial kriging variances obtained by the robust network and by the mono objective criterion for Erosivity factor mapping

Conclusions

The robust optimization approach considering IDF curves parameters and kriging was applied to locate the best sites for implementing new rain gauges North Tunisia. The method is based on the choice of a time horizon and on objective functions involving IDF-return periods and parameters. Accordingly, robust optimization results are compared to two mono objective criteria (rainfall intensity mapping and erosivity factor mapping) using a single extreme rainfall event analysis. The comparison of results highlights that the percentage of gain in the robust optimisation is lower or equal to that obtained in the case of the mono objective criterion. Nevertheless, the most advantage of the robust optimisation lies in the fact that it allows to overcome the problem of elaborating rainfall event database in case of adopting the classical approach of variance-reduction method based on single rainfall patterns.

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